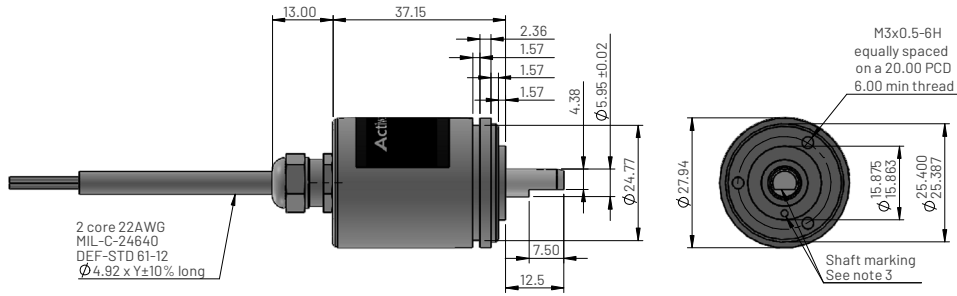


# VRP1120 Current Output - Rotary potentiometer

High performance series

## Dimensions for VRP1120 - Synchro mounting with rear cable exit



## Ordering information

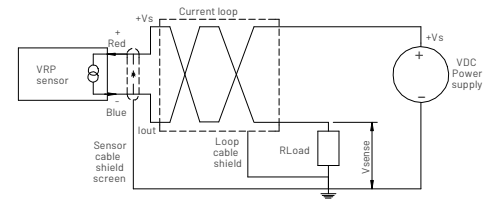
VRP1120-11-XXX-Y-AA1

Electrical angle in degrees   
 Cable length 0 to 9   
 0 - 0.5m, 1 - 1m ... 9 - 9m  
 Output direction (viewed on shaft)   
 A = anticlockwise  
 Output signal   
 A1 = 4-20mA

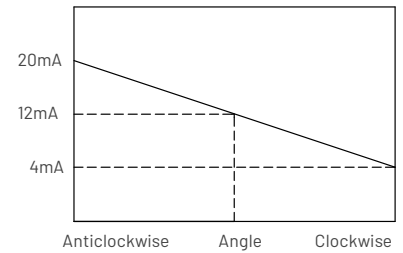
## Electrical and mechanical specification

Parameters	Values	Units	Notes
<b>Mechanical specification</b>			
Electrical angle ( $\pm 2^\circ$ )	100, 130, 350	$^\circ$	
Mechanical travel	360 Continuous	$^\circ$	
Sensor weight (excluding cable)	60	grams	
<b>Performance specification</b>			
Non-linearity	$< \pm 0.50$	%FS	2
Resolution	Infinite		
Thermal drift	$\pm 0.01$ TBD	%FS/ $^\circ\text{C}$	
<b>Electrical specification</b>			
Input voltage (+Vs)	12 to 40	VDC	
Line regulation	$< 0.002$	%FS/V	7
Reverse polarity (+Vs)	-60	VDC	
Output current (Iout)	2 wire 4-20	mA	
Sensitivity $< \pm 2\%$	0.160, 0.120, 0.046	mA/ $^\circ$	2
Loop resistance (max)	(+Vs-8V)/0.02A	ohms	8
Output noise and ripple	$< 0.05$	%FS RMS	
Electrical connections	2 core x 22AWG (screened) Zerohal jacket		
Cable length (max)	0.5 to 9.0	m	9
<b>Environmental specification</b>			
Operating temperature range	-30 to +105	$^\circ\text{C}$	
Environmental	IP67		
Materials	Sensor	Case - Anodised aluminium alloy 6063-T5, Shaft - Stainless steel	
	Cable gland	Nickel plated brass	

## Electrical connections (see note 1)



## VRP mA output schematic



## Notes

1. Incorrect wiring may cause internal damage.
2. Non-linearity error and sensitivity is calculated from least squares best fit method.
3. When shaft flat is facing case shaft mark the instrument is mid-travel.
4. Average thermal drift over operating temperature range.
5. Nominal bandwidth (-3dB) with a 1st order (-20dB/decade) roll-off.
6. Within 20 seconds of power on condition and over 30 minutes period. (Whilst delta temperature sensor  $< 2^\circ\text{C}$ )
7. When +Vs = +12VDC to +30VDC.
8. Includes all wiring resistance and RLoad resistance.
9. Includes all wiring between sensor and RLoad.
10. General dimension tolerance is  $\pm 0.25$ .

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